# Известия НАН Армении, Математика, том 58, н. 3, 2023, стр. 92 – 100. AN APPLICATION OF RICCERI THEOREM IN SOLVING BOUNDARY VALUE PROBLEMS

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Abstract. Professor Ricceri very recently in the interesting paper has obtained a global minima theorem. In this paper, we will provide an application of this theorem.

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## 1. INTRODUCTION

Authors in [1], considered a class of semilinear elliptic systems of the form

$$\begin{cases} -\operatorname{div}(h_1(x)\nabla u) = \lambda F_u(x, u, v) & \text{in } \Omega, \\ -\operatorname{div}(h_2(x)\nabla v) = \lambda F_v(x, u, v) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega \end{cases}$$

where  $\Omega$  is a bounded domain in  $\mathbb{R}^N$   $(N \ge 2)$  and  $\lambda$  is a positive parameter. Indeed, using the Mountain pass theorem, they proved if  $\lambda$  is large enough the above system has at least two nonnegative solutions. Such problems come from the consideration of standing waves in anisotropic Schrödinger systems (see [15]). These equations appear in many topics of applied physics, such as nuclear physics, field theory, solid waves and problems of false vacuum see ([2, 3]).

Ricceri in [4] established following theorem:

**Theorem 1.1.** Let X be a topological space,  $(Y, \langle \cdot, \cdot \rangle)$  a real Hilbert space,  $T \subseteq Y$  a convex set dense in Y and  $I: X \to \mathbb{R}$ ,  $\varphi: X \to Y$  two functions such that, for each  $y \in T$ , the function  $x \to I(x) + \langle \varphi(x), y \rangle$  is lower semicontinuous and inf-compact. Moreover, assume that there exists a point  $x_0 \in X$ , with  $\varphi(x_0) \neq 0$  such that

- $(\varphi_1)$   $x_0$  is a global minimum of both functions I and  $\|\varphi(\cdot)\|$ ;
- $(\varphi_2) \inf_{x \in X} \langle \varphi(x), \varphi(x_0) \rangle < \|\varphi(x_0)\|^2.$

Then, for each convex set  $S \subseteq T$  dense in Y, there exists  $\tilde{y} \in S$  such that the functional  $x \to I(x) + \langle \varphi(x), \tilde{y} \rangle$  has at least two global minima in X.

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Then, he presented an application of this theorem in solving a system of elliptic equations. Indeed, he proved following theorem.

Let  $\Omega \subseteq \mathbb{R}^n$   $(n \geq 2)$  is a bounded domain with smooth boundary. We denote by  $\mathcal{A}_1$  the class of all functions  $\Phi : \Omega \times \mathbb{R}^2 \to \mathbb{R}$  which are measurable in  $\Omega$ ,  $C^1$  in  $\mathbb{R}^2$  and satisfy

$$\sup_{v,v)\in\Omega\times\mathbb{R}^2} \frac{|\Phi_u(x,u,v)| + |\Phi_v(x,u,v)|}{1+|u|^m+|v|^m} < +\infty$$

where  $\Phi_u$  (resp.  $\Phi_v$ ) denoting the derivative of  $\Phi$  with respect to u (resp. v) and m > 0 with  $m < \frac{n+2}{n-2}$  when n > 2.

**Theorem 1.2.** Let  $F_1, G_1, K_1 \in A_1$ , with  $K_1(x, 0, 0) = 0$  for all  $x \in \Omega$ , satisfy the following conditions:

- $\begin{aligned} (k_1) & \text{there is } \eta \in (0, \frac{\lambda_1}{2}) \text{ such that } K_1(x, s, t) \leq \eta(s^2 + t^2) \text{ for all } x \in \Omega, \, s, t \in \mathbb{R}, \\ & \text{where } \lambda_1 = \inf_{u \in H_0^1(\Omega) \setminus \{0\}} \frac{\int_{\Omega} |\nabla u|^2 dx}{\int_{\Omega} |u|^2 dx}; \\ (f_1) & \lim_{s^2 + t^2 \to +\infty} \frac{\sup_{x \in \Omega} (|F_1(x, s, t)| + |G_1(x, s, t)|)}{s^2 + t^2} = 0; \end{aligned}$
- $(f_2) \ one \ has \ \mathrm{meas}(\{x\in \Omega: |F_1(x,0,0)|^2+|G_1(x,0,0)|^2>0\})>0 \\ and$

$$|F_1(x,0,0)|^2 + |G_1(x,0,0)|^2 \le |F_1(x,s,t)|^2 + |G_1(x,s,t)|^2$$

for all  $x \in \Omega$ ,  $s, t \in \mathbb{R}$ ;

(x,u)

 $(f_3)$  one has

$$\max(\{x \in \Omega : \inf_{(s,t) \in \mathbb{R}^2} (|F_1(x,0,0)| F_1(x,s,t) + |G_1(x,0,0)|^2 G_1(x,s,t)) \\ < |F_1(x,0,0)|^2 + |G_1(x,0,0)|^2 \}) > 0.$$

Then, for every convex set  $S_1 \subseteq L^{\infty}(\Omega) \times L^{\infty}(\Omega)$  dense in  $L^2(\Omega) \times L^2(\Omega)$ , there exists  $(\sigma_1, \varsigma_1) \in S_1$  such that the problem

$$\begin{cases} -\Delta u = \sigma_1(x)F_{1u}(x, u, v) + \varsigma_1(x)G_{1u}(x, u, v) + K_{1u}(x, u, v) & \text{in } \Omega, \\ -\Delta v = \sigma_1(x)F_{1v}(x, u, v) + \varsigma_1(x)G_{1v}(x, u, v) + K_{1v}(x, u, v) & \text{in } \Omega, \\ u = v = 0 & \text{on } \partial\Omega \end{cases}$$

has at least three weak solutions, two of which are global minima in  $H_0^1(\Omega) \times H_0^1(\Omega)$ of the functional

$$(u,v) \rightarrow \frac{1}{2} \left( \int_{\Omega} |\nabla u|^2 dx + \int_{\Omega} |\nabla v|^2 dx \right)$$
$$- \int_{\Omega} (\sigma_1(x) F_1(x, u, v) + \varsigma_1(x) G_1(x, u, v) + K_1(x, u(x), v(x))) dx.$$

Using Theorem 1.1, the author proved above theorem with the following choices: X is the space  $H_0^1(\Omega) \times H_0^1(\Omega)$  and Y is  $L^2(\Omega) \times L^2(\Omega)$ .

In this paper, motivated by [1, 4], we give an application of Theorem 1.1. Indeed, in Section 2, we will prove a new version of Theorem 1.2 with the choice X =

 $H_0^1(\Omega, h_1) \times H_0^1(\Omega, h_2)$ , where  $h_i : \Omega \to [0, +\infty)$ ,  $h_i \in L_{loc}^1$  (i = 1, 2). We define the Hilbert spaces  $H_0^1(\Omega, h_1)$  and  $H_0^1(\Omega, h_2)$  as the closures of  $C_0^\infty(\Omega)$  with respect to the norms

$$||u||_{h_1} = \left(\int_{\Omega} h_1(x) |\nabla u|^2 dx\right)^{\frac{1}{2}}$$

for all  $u \in C_0^{\infty}(\Omega)$  and

$$||v||_{h_2} = \left(\int_{\Omega} h_2(x) |\nabla v|^2 dx\right)^{\frac{1}{2}}$$

for all  $v \in C_0^{\infty}(\Omega)$ , respectively. It is clear that  $X = H_0^1(\Omega, h_1) \times H_0^1(\Omega, h_2)$  is a Hilbert space under the norm  $||w||_X = ||u||_{h_1} + ||v||_{h_2}$  for all  $w = (u, v) \in X$ .

We denote by  $\mathcal{A}_2$  the class of  $C^1$  functions  $A : \Omega \times \mathbb{R}^2 \to \mathbb{R}$  which possess the following properties:

there exist two positive constants  $c_1$  and  $c_2$  such that

(1.1) 
$$|A_t(x,s,t)| \le c_1 s^{\gamma} t^{\delta+1}, \qquad |A_s(x,s,t)| \le c_2 s^{\gamma+1} t^{\delta}$$

for all  $(t,s) \in \mathbb{R}^2$ , a.e  $x \in \Omega$  and some constants  $\gamma, \delta > 1$  with  $\frac{\gamma+1}{p} + \frac{\delta+1}{q} = 1$ ,  $\frac{\gamma+1}{2_{\alpha}^*} + \frac{\delta+1}{2_{\beta}^*} < 1$  and,  $\gamma + 1 , <math>\delta + 1 < q < 2_{\beta}^* = \frac{2n}{n-2+\beta}$ , where  $p, q, \alpha, \beta$  are positive constants and  $\alpha, \beta \in (0, 2)$ .

Throughout this paper, we assume the functions  $h_1$  and  $h_2$  satisfying the following conditions:

- (**H**<sub>1</sub>) The function  $h_1 : \Omega \to [0, +\infty)$  belongs to  $L^1_{loc}(\Omega)$  and there exists a constant  $\alpha \ge 0$  such that  $\liminf_{x \to \infty} |x z|^{-\alpha} h_1(x) > 0$  for all  $z \in \overline{\Omega}$ ,
- (**H**<sub>2</sub>) The function  $h_2 : \Omega \to [0, +\infty)$  belongs to  $L^1_{loc}(\Omega)$  and there exists a constant  $\beta \ge 0$  such that  $\liminf_{x \to z} |x z|^{-\beta} h_2(x) > 0$  for all  $z \in \overline{\Omega}$ .

#### 2. Main results

Here, we will prove a new version of Theorem 1.2 with the choice  $X = H_0^1(\Omega, h_1) \times H_0^1(\Omega, h_2)$ , where  $h_i : \Omega \to [0, +\infty)$ ,  $h_i \in L_{loc}^1$  (i = 1, 2).

**Theorem 2.1.** Assume that the hypotheses  $(\mathbf{H_1})$  and  $(\mathbf{H_2})$  are satisfied. Also, let  $F_2, G_2, K_2 \in \mathcal{A}_2$ , with  $K_2(x, 0, 0) = 0$  for all  $x \in \Omega$ , satisfy the following conditions:

 $\begin{aligned} (k_2) \ there \ is \ a \ \in \ (0, \frac{\lambda_1}{2}\theta) \ such \ that \ K_2(x, s, t) \ \le \ a|s|^{\gamma+1}|t|^{\delta+1} \ for \ all \ x \ \in \ \Omega, \\ s, t \ \in \ \mathbb{R}, \ where \ \lambda_1 \ = \ \inf_{w = (u,v) \in X \setminus \{(0,0)\}} \ \frac{\int_{\Omega} \left(\frac{\gamma+1}{p}h_1(x)|\nabla u|^2 + \frac{\delta+1}{q}h_2(x)|\nabla v|^2\right) dx}{\int_{\Omega} |u|^{\gamma+1}|v|^{\delta+1} dx} \\ and \ \theta \ = \ \frac{1}{2\max\left\{\frac{\gamma+1}{p}, \frac{\delta+1}{q}\right\}}, \\ (f_4) \\ \lim_{s^2 + t^2 \to +\infty} \ \frac{\sup_{x \in \Omega} \left(|F_2(x, s, t)| + |G_2(x, s, t)|\right)}{s^2 + t^2} = 0; \end{aligned}$ 

AN APPLICATION OF RICCERI THEOREM ...

 $(f_{5})$ 

meas 
$$\left(\left\{x \in \Omega : \left|F_2(x,0,0)\right|^2 + \left|G_2(x,0,0)\right|^2 > 0\right\}\right) > 0$$

and

$$|F_2(x,0,0)|^2 + |G_2(x,0,0)|^2 \le |F_2(x,s,t)|^2 + |G_2(x,s,t)|^2$$

for all  $s, t \in \mathbb{R}, x \in \Omega$ ;

 $(f_6)$  the set of all  $x \in \Omega$  that satisfy following condition

$$\inf_{(s,t)\in\mathbb{R}^2} \left( F_2(x,0,0)F_2(x,s,t) + G_2(x,0,0)G_2(x,s,t) \right) \right) < \left| F_2(x,0,0) \right|^2 + \left| G_2(x,0,0) \right|^2$$

has positive measure.

Then, for every convex set  $S_2 \subseteq L^{\infty}(\Omega) \times L^{\infty}(\Omega)$  dense in  $L^2(\Omega) \times L^2(\Omega)$ , there exists  $(\sigma_2, \varsigma_2) \in S_2$  such that the problem

(2.1)  

$$\begin{cases}
-\operatorname{div}(h_1(x)\nabla u) = \sigma_2(x)F_{2u}(x, u, v) + \varsigma_2(x)G_{2u}(x, u, v) + K_{2u}(x, u, v) & \text{in } \Omega, \\
-\operatorname{div}(h_2(x)\nabla v) = \sigma_2(x)F_{2v}(x, u, v) + \varsigma_2(x)G_{2v}(x, u, v) + K_{2v}(x, u, v) & \text{in } \Omega, \\
u = v = 0 & \text{on } \partial\Omega
\end{cases}$$

has at least three weak solutions, two of which are global minima in X of the functional

$$(u,v) \to \frac{1}{2} \left( \int_{\Omega} h_1(x) |\nabla u|^2 dx + \int_{\Omega} h_2(x) |\nabla v|^2 dx \right) \\ - \int_{\Omega} (\sigma_2(x) F_2(x, u, v) + \varsigma_2(x) G_2(x, u, v) + K_2(x, u(x), v(x))) dx.$$

**Proof.** In order to apply Theorem 1.1 to our problem, we take  $X = H_0^1(\Omega, h_1) \times H_0^1(\Omega, h_2)$ , where endowed with the weak topology induced by the scalar product

$$\langle (u,v), (\zeta,\tau) \rangle_X = \int_{\Omega} (h_1(x)\nabla u(x)\nabla\zeta(x) + h_2(x)\nabla v(x)\nabla\tau(x))dx;$$

also, Y is the space  $L^2(\Omega) \times L^2(\Omega)$  with the scalar product

$$\langle (\kappa, \omega), (h, k) \rangle_Y = \int_{\Omega} \kappa(x) h(x) dx + \int_{\Omega} \omega(x) k(x) dx$$

and T is  $L^\infty(\Omega)\times L^\infty(\Omega).$  We define the functional  $I:X\to\mathbb{R}$ 

$$I(u,v) = \frac{1}{2} \left( \int_{\Omega} h_1(x) |\nabla u|^2 dx + \int_{\Omega} h_2(x) |\nabla v|^2 dx \right) - \int_{\Omega} K_2(x, u(x), v(x)) dx.$$

for all  $(u, v) \in X$ . Also, let  $x_0$  is the zero of X and  $\varphi$  be the function defined by

$$\varphi(u,v) = \left(F_2(\cdot, u(\cdot), v(\cdot)), G_2(\cdot, u(\cdot), v(\cdot))\right)$$

for all  $(u, v) \in X$ . We check that the assumptions of Theorem 1.1 are satisfied. At first, from  $(f_5)$ , we observe that

$$\|\varphi(0,0)\|_{Y}^{2} = \int_{\Omega} \left|F_{2}(x,0,0)\right|^{2} dx + \int_{\Omega} \left|G_{2}(x,0,0)\right|^{2} dx > 0$$
95

and

$$\|\varphi(0,0)\|_{Y}^{2} \leq \|\varphi(u,v)\|_{Y}^{2}$$

for all  $(u, v) \in X$ . Moreover, from  $(k_2)$ , we obtain that

$$\int_{\Omega} K_2(x, u(x), v(x)) dx \le a \int_{\Omega} (|u(x)|^{\gamma+1} |v(x)|^{\delta+1}) dx$$
$$\le \frac{a}{\lambda_1} \int_{\Omega} \left( \frac{\gamma+1}{p} h_1(x) |\nabla u(x)|^2 + \frac{\delta+1}{q} h_2(x) |\nabla v(x)|^2 \right) dx$$

for all  $(u, v) \in X$  and so, one has

(2.2) 
$$I(u,v) \ge \frac{\theta}{2} \int_{\Omega} \left( \frac{\gamma+1}{p} h_1(x) |\nabla u(x)|^2 + \frac{\delta+1}{q} h_2(x) |\nabla v(x)|^2 \right) dx$$
$$\ge \frac{\theta}{2} \frac{\gamma+1}{p} ||u||_{h_1}^2 + \frac{\theta}{2} \frac{\delta+1}{q} ||v||_{h_2}^2$$

for all  $(u, v) \in X$ . Take  $K_2(x, 0, 0) = 0$  and  $\frac{a}{\lambda_1} < \frac{\theta}{2}$  into account, from (2.2) we obtain (0, 0) is a global minimum of I in X. So, condition  $(\varphi_1)$  of Theorem 1.1 is satisfied. Also, by condition  $(f_3)$ , we find  $(\varphi_2)$  is satisfied. Finally, fix  $\sigma_2, \varsigma_2 \in \mathbb{R}$ . Clearly, the function

$$(x,s,t) \to \sigma_2(x)F(x,s,t) + \varsigma_2(x)G(x,s,t) + K(x,s,t)$$

belongs to  $\mathcal{A}_2$ , and so the functional

$$(u, v) \to I(u, v) + \langle \varphi(u, v), (\sigma_2, \varsigma_2) \rangle_Y$$

is sequentially weakly lower semicontinuous in X. Indeed, let  $\{w_m\} = \{(u_m, v_m)\}$ be a sequence that converges weakly to w = (u, v) in X. We have

$$\begin{split} &\int_{\Omega} \sigma_2(x) [F(x, u_m, v_m) - F(x, u, v)] dx + \int_{\Omega} \varsigma_2(x) [G(x, u_m, v_m) - G(x, u, v)] dx \\ &= \int_{\Omega} \sigma_2(x) \nabla F(x, \theta_m(w_m - w))(w_m - w) dx + \\ &\int_{\Omega} \varsigma_2(x) \nabla G(x, \rho_m(w_m - w))(w_m - w) dx \\ &= \int_{\Omega} \sigma_2(x) F_u(x, u + \theta_{1,m}(u_m - u), v + \theta_{2,m}(v_m - v))(u_m - u) dx \\ &+ \int_{\Omega} \sigma_2(x) F_v(x, u + \theta_{1,m}(u_m - u), v + \theta_{2,m}(v_m - v))(v_m - v) dx \\ &+ \int_{\Omega} \varsigma_2(x) G_u(x, u + \rho_{1,m}(u_m - u), v + \rho_{2,m}(v_m - v))(u_m - u) dx \\ &+ \int_{\Omega} \varsigma_2(x) G_v(x, u + \rho_{1,m}(u_m - u), v + \rho_{2,m}(v_m - v))(u_m - v) dx \end{split}$$

where  $\theta_m = (\theta_{1,m}, \theta_{2,m}), \rho_m = (\rho_{1,m}, \rho_{2,m})$  and  $0 \le \theta_{1,m}(x), \theta_{2,m}(x), \rho_{1,m}(x), \rho_{2,m}(x) \le 1$  for all  $x \in \Omega$ . Now, take (1.1) and Hölder's inequality into account, we deduce

that there exist  $c_1, c_2, c_3, c_4 > 0$  such that

$$\begin{split} & \left| \int_{\Omega} \sigma_{2}(x) [F(x, u_{m}, v_{m}) - F(x, u, v)] dx + \int_{\Omega} \varsigma_{2}(x) [G(x, u_{m}, v_{m}) - G(x, u, v)] dx \right| \\ & \leq \|\sigma_{2}\|_{\infty} \int_{\Omega} \left| F_{u}(x, u + \theta_{1,m}(u_{m} - u), v + \theta_{2,m}(v_{m} - v)) \right| |u_{m} - u| dx \\ & + \|\sigma_{2}\|_{\infty} \int_{\Omega} \left| F_{v}(x, u + \theta_{1,m}(u_{m} - u), v + \theta_{2,m}(v_{m} - v)) \right| |v_{m} - v| dx \\ & + \|\varsigma_{2}\|_{\infty} \int_{\Omega} \left| G_{u}(x, u + \rho_{1,m}(u_{m} - u), v + \rho_{2,m}(v_{m} - v)) \right| |u_{m} - u| dx \\ & + \|\varsigma_{2}\|_{\infty} \int_{\Omega} \left| G_{v}(x, u + \rho_{1,m}(u_{m} - u), v + \rho_{2,m}(v_{m} - v)) \right| |v_{m} - v| dx \\ & \leq c_{1} \|\sigma_{2}\|_{\infty} \int_{\Omega} \left| u + \theta_{1,m}(u_{m} - u) \right|^{\gamma} |v + \theta_{2,m}(v_{m} - v)|^{\delta+1} |u_{m} - u| dx \\ & + c_{2} \|\sigma_{2}\|_{\infty} \int_{\Omega} \left| u + \theta_{1,m}(u_{m} - u) \right|^{\gamma+1} |v + \theta_{2,m}(v_{m} - v)|^{\delta} |v_{m} - v| dx \\ & + c_{3} \|\varsigma_{2}\|_{\infty} \int_{\Omega} \left| u + \rho_{1,m}(u_{m} - u) \right|^{\gamma} |v + \rho_{2,m}(v_{m} - v)|^{\delta+1} |u_{m} - u| dx \\ & + c_{4} \|\varsigma_{2}\|_{\infty} \int_{\Omega} \left| u + \rho_{1,m}(u_{m} - u) \right|^{\gamma+1} |v + \rho_{2,m}(v_{m} - v)|^{\delta} |v_{m} - v| dx. \end{split}$$

So, we have

$$\begin{split} \left| \int_{\Omega} \sigma_{2}(x) [F(x, u_{m}, v_{m}) - F(x, u, v)] dx + \int_{\Omega} \varsigma_{2}(x) [G(x, u_{m}, v_{m}) - G(x, u, v)] dx \right| \\ &\leq c_{1} \|\sigma_{2}\|_{\infty} \|u + \theta_{1,m}(u_{m} - u)\|_{L^{p}(\Omega)}^{\gamma} \|v + \theta_{2,m}(v_{m} - v))\|_{L^{q}(\Omega)}^{\delta+1} \|u_{m} - u\|_{L^{p}(\Omega)} \\ &+ c_{2} \|\sigma_{2}\|_{\infty} \|u + \theta_{1,m}(u_{m} - u)\|_{L^{p}(\Omega)}^{\gamma+1} \|v + \theta_{2,m}(v_{m} - v))\|_{L^{q}(\Omega)}^{\delta} \|v_{m} - v\|_{L^{q}(\Omega)} \\ &+ c_{3} \|\varsigma_{2}\|_{\infty} \|u + \rho_{1,m}(u_{m} - u)\|_{L^{p}(\Omega)}^{\gamma} \|v + \rho_{2,m}(v_{m} - v))\|_{L^{q}(\Omega)}^{\delta} \|u_{m} - u\|_{L^{p}(\Omega)} \\ &+ c_{4} \|\varsigma_{2}\|_{\infty} \|u + \rho_{1,m}(u_{m} - u)\|_{L^{p}(\Omega)}^{\gamma+1} \|v + \rho_{2,m}(v_{m} - v))\|_{L^{q}(\Omega)}^{\delta} \|v_{m} - v\|_{L^{q}(\Omega)}. \end{split}$$

Since  $2 < \gamma + 1 < p < 2^*_{\alpha}$  and  $2 < \gamma + 1 < q < 2^*_{\beta}$ , by the compact embedding  $X \hookrightarrow L^p(\Omega) \times L^q(\Omega)$ , the sequence  $\{w_m\}$  convergence strongly to w = (u, v) in the space  $L^p(\Omega) \times L^q(\Omega)$ , i.e., the sequence  $\{u_m\}$  converges strongly to u in  $L^p(\Omega)$  and  $\{v_m\}$  converges strongly to v in  $L^q(\Omega)$ . Hence, it is easy to see that the sequences  $\{\|u + \theta_{1,m}(u_m - u)\|_{L^p(\Omega)}\}, \{\|v + \theta_{2,m}(v_m - v)\|_{L^q(\Omega)}\}, \{\|u + \rho_{1,m}(u_m - u)\|_{L^p(\Omega)}\}$  and  $\{\|v + \rho_{2,m}(v_m - v)\|_{L^q(\Omega)}\}$  are bounded. Thus, it follows

(2.3) 
$$\lim_{m \to \infty} \int_{\Omega} [\sigma_2(x)F(x, u_m, v_m) + \varsigma_2(x)G(x, u_m, v_m)]dx$$
$$= \int_{\Omega} [\sigma_2F(x, u, v) + \varsigma_2G(x, u, v)]dx.$$

Using similar arguments as those used above, we obtain that

(2.4) 
$$\lim_{m \to \infty} \int_{\Omega} K(x, u_m, v_m) dx = \int_{\Omega} K(x, u, v) dx$$

By the weak lower semicontinuity of the norms in the spaces  $H_0^1(\Omega, h_1)$  and  $H_0^1(\Omega, h_2)$ we deduce that

(2.5)  
$$\lim_{m \to \infty} \inf \int_{\Omega} [h_1(x) |\nabla u_m|^2 + h_2(x) |\nabla v_m|^2] dx \ge \int_{\Omega} [h_1(x) |\nabla u|^2 + h_2(x) |\nabla v|^2] dx.$$

Hence, relations (2.3), (2.4) and (2.5) imply that the function

$$(u, v) \to I(u, v) + \langle \varphi(u, v), (\sigma_2, \varsigma_2) \rangle_Y$$

is sequentially weakly lower semicontinuous in X.

We now prove that the function

$$(u, v) \to I(u, v) + \langle \varphi(u, v), (\sigma_2, \varsigma_2) \rangle_Y$$

is coercive. Put

$$b = \max\{\|\sigma_2\|_{L^{\infty}(\Omega)}, \|\varsigma_2\|_{L^{\infty}(\Omega)}\}$$

and fix  $\epsilon>0$  such that

(2.6) 
$$\epsilon < \min\left\{\frac{\lambda_1(h_1)}{b}\frac{\theta(\gamma+1)}{2p}, \frac{\lambda_1(h_2)}{b}\frac{\theta(\delta+1)}{2q}\right\},$$

where

$$\lambda_1(h_i) := \inf_{\phi \in H^1_0(\Omega, h_i) \setminus \{0\}} \frac{\int_\Omega h_i(x) |\nabla \phi|^2}{\int_\Omega |\phi|^2 dx}, \qquad i = 1, 2.$$

From  $(f_4)$ , there is  $c_{\epsilon} > 0$  such that

$$|F(x, s, t)| + |G(x, s, t)| \le \epsilon(|s|^2 + |t|^2) + c_{\epsilon}$$

for all  $(x, s, t) \in \Omega \times \mathbb{R}^2$ . Hence, in view of (2.2), for each  $(u, v) \in H_0^1(\Omega, h_1) \times H_0^1(\Omega, h_2)$ , we conclude that

$$\begin{split} I(u,v) + \langle \varphi(u,v), (\sigma_{2},\varsigma_{2}) \rangle_{Y} &\geq \frac{\theta}{2} \frac{\gamma+1}{p} \|u\|_{h_{1}}^{2} + \frac{\theta}{2} \frac{\delta+1}{q} \|v\|_{h_{2}}^{2} \\ &- \int_{\Omega} |\sigma_{2}(x)F(x,u(x),v(x)) + \varsigma_{2}(x)G(x,u(x),v(x))| dx \\ &\geq \frac{\theta}{2} \frac{\gamma+1}{p} \|u\|_{h_{1}}^{2} + \frac{\theta}{2} \frac{\delta+1}{q} \|v\|_{h_{2}}^{2} - b\epsilon \int_{\Omega} (|u(x)|^{2} + |v(x)|^{2}) dx - bc_{\epsilon} \mathrm{meas}(\Omega) \\ &\geq \frac{\theta}{2} \frac{\gamma+1}{p} \|u\|_{h_{1}}^{2} + \frac{\theta}{2} \frac{\delta+1}{q} \|v\|_{h_{2}}^{2} - b\epsilon \left(\frac{1}{\lambda_{1}(h_{1})} \int_{\Omega} h_{1}(x) |\nabla u(x)|^{2} dx + \frac{1}{\lambda_{1}(h_{2})} \int_{\Omega} h_{2}(x) |\nabla v(x)|^{2} dx \right) - bc_{\epsilon} \mathrm{meas}(\Omega) \\ &\geq \left(\frac{\theta(\gamma+1)}{2p} - \frac{b\epsilon}{\lambda_{1}(h_{1})}\right) \int_{\Omega} h_{1}(x) |\nabla u|^{2} dx \\ &+ \left(\frac{\theta(\delta+1)}{2q} - \frac{b\epsilon}{\lambda_{1}(h_{2})}\right) \int_{\Omega} h_{2}(x) |\nabla v|^{2} dx - bc_{\epsilon} \mathrm{meas}(\Omega). \end{split}$$

bearing in mind the relation (2.6), we have  $\frac{\theta(\gamma+1)}{2p} - \frac{b\epsilon}{\lambda_1(h_1)}, \frac{\theta(\delta+1)}{2q} - \frac{b\epsilon}{\lambda_1(h_2)} > 0$ , and so

$$\lim_{\|(u,v)\|_X \to +\infty} (I(u,v) + \langle \varphi(u,v), (\sigma_2,\varsigma_2) \rangle_Y) = +\infty,$$

as claimed. In virtue of Eberlein-Smulyan theorem, this also follows that the functional  $I(u, v) + \langle \varphi(u, v), (\sigma_2, \varsigma_2) \rangle_Y$  is weakly lower semicontinuous. Thus, the assumptions of Theorem 1.1 are verified. Therefore, for each convex set  $S_2 \subseteq L^{\infty}(\Omega) \times L^{\infty}(\Omega)$ , there exists  $(\sigma_2, \varsigma_2) \in S_2$ , such that the functional

$$\begin{aligned} (u,v) \to &\frac{1}{2} \bigg( \int_{\Omega} h_1(x) |\nabla u|^2 dx + \int_{\Omega} h_2(x) |\nabla v|^2 dx \bigg) \\ &- \int_{\Omega} (\sigma_2(x) F_2(x, u, v) + \varsigma_2(x) G_2(x, u, v) + K_2(x, u(x), v(x))) dx. \end{aligned}$$

has at least two global minima in X and by Example 38.25 of [5] it admits at least three critical points. Hence, the conclusion is achieved.  $\Box$ 

**Remark 2.1.** Assume that  $w = (u, v) \in X$  is a weak solution of problem (2.1), then  $u \ge 0$  and  $v \ge 0$  in  $\Omega$ . Indeed, from our assumptions in Theorem 2.1, we have

$$\begin{split} 0 &= \int_{\Omega} (h_1(x)\nabla u \cdot \nabla u^- + h_2(x)\nabla v \cdot \nabla v^-) dx \\ &- \int_{\Omega} \sigma_2(x) (F_{2u}(x, u, v)u^- + F_{2v}(x, u, v)v^-) dx \\ &- \int_{\Omega} \varsigma_2(x) (G_{2u}(x, u, v)u^- + G_{2v}(x, u, v)v^-) dx \\ &+ \int_{\Omega} (K_{2u}(x, u, v)u^- + K_{2v}(x, u, v)v^-) dx \\ &= \|u^-\|_{h_1}^2 + \|v^-\|_{h_2}^2 \ge \lambda_1(h_1) \int_{\Omega} |u^-|^2 dx + \lambda_1(h_2) \int_{\Omega} |v^-|^2 dx, \end{split}$$

which implies that  $u(x) \ge 0$  and  $v(x) \ge 0$  for a.e.  $x \in X$ .

A special case of our main result is the following theorem.

**Theorem 2.2.** Let  $K_3 \in A_2$ , with  $K_3(x, 0, 0) = 0$  for all  $x \in \Omega$ , satisfies  $(k_2)$ . Then, for every convex set  $S_3 \subseteq \mathbb{R}^2$ , there exists  $(\sigma_3, \varsigma_3) \in S_3$  such that the problem

$$\begin{aligned} &-\operatorname{div}(|x|\nabla u) \\ &= (\sigma_3(x)\cos(uv\sqrt{uv}) - \varsigma_3(x)\sin(uv\sqrt{uv}))\frac{3\sqrt{uv^3}}{2} + K_{3u}(x,u,v) & \text{in } \Omega, \\ &-\operatorname{div}(|x|\nabla v) \\ &= (\sigma_3(x)\cos(uv\sqrt{uv}) - \varsigma_3(x)\sin(uv\sqrt{uv}))\frac{3\sqrt{u^3v}}{2} + K_{3v}(x,u,v) & \text{in } \Omega, \\ &u = v = 0, & \text{on } \partial\Omega \end{aligned}$$

has at least three weak solutions, two of which are global minima in  $H_0^1(\Omega, |x|) \times H_0^1(\Omega, |x|)$  of the functional

$$(u,v) \rightarrow \frac{1}{2} \left( \int_{\Omega} |x| |\nabla u|^2 dx + \int_{\Omega} |x| |\nabla v|^2 dx \right) \\ - \int_{\Omega} (\sigma_3(x) \sin(uv\sqrt{uv}) + \varsigma_3(x) \cos(uv\sqrt{uv}) + K_3(x,u(x),v(x))) dx.$$

**Proof.** Apply Theorem 2.1 to the functions  $F_2, G_2 : \mathbb{R}^2 \to \mathbb{R}$  defined by  $F_2(s,t) = \sin(st\sqrt{st})$  and  $G_2(s,t) = \cos(st\sqrt{st})$  for all  $(s,t) \in \mathbb{R}^2$ .

**Conclusion.** Due to the generality of the Theorem 1.1, it can be applied to many different situations.

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