

A GENERALIZATION OF 4-DIMENSIONAL LOCALLY CONFORMAL FLAT WALKER MANIFOLDS

S. AZIMPOUR, M. CHAICHI AND M. TOOMANIAN

University of Tabriz, Tabriz, Iran
E-mail: *sohrab_azimpour@yahoo.com, Toomanian@tabrizu.ac.ir*
University of Payame Noor of Tabriz, Tabriz, Iran
E-mail: *chaichi3@hotmail.com*

АННОТАЦИЯ. A 4-dimensional Walker metrics with $c = 0$ on a semi-Riemannian manifold M have been investigated by E. García-Río and Y. Matsushita. The case $c = \text{constant}$ has been studied in [1]. In this paper we generalize these notions to the case of non-constant c . We find the form of the defining functions that makes this manifold similar to locally conformal flat 4-dimensional Walker manifold.

1. INTRODUCTION

A Walker n -manifold admits a field of parallel null r -planes, with $r \leq \frac{n}{2}$. The canonical form of a metric studied by Walker [5] contains three functions $a(x, y, z, t)$, $b(x, y, z, t)$ and $c(x, y, z, t)$. We consider 4-dimensional Walker manifolds with parallel null 2-planes. In [3] locally conformal flat Walker manifolds were investigated in the restricted form of metric when $c(x, y, z, t) = 0$. The case $c = \text{constant}$ is studied in [1]. In this paper following [1] and [3], we focus upon the case of arbitrary non-constant $c = c(x, y, z, t)$, and investigate locally conformal flat 4-dimensional Walker manifolds admitting parallel null 2-planes.

Definition 1. *A Walker manifold is a triad (M, g, D) of an n -dimension manifold M , an indefinite metric g and an r -dimensional parallel distribution D .*

If $\dim M = 4$ and $\dim D = 2$, g has the signature $(- -++)$ and in suitable coordinates

$$(1.1) \quad g(x, y, z, t) = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & a(x, y, z, t) & c(x, y, z, t) \\ 0 & 1 & c(x, y, z, t) & b(x, y, z, t) \end{pmatrix}$$

for some functions $a(x, y, z, t)$, $b(x, y, z, t)$, $c(x, y, z, t)$ and where $D = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\rangle$ (cf.[5,6]). The plane D is strictly parallel if and only if

$$(1.2) \quad g(x, y, z, t) = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & a(z, t) & c(z, t) \\ 0 & 1 & c(z, t) & b(z, t) \end{pmatrix}.$$

In this case the coordinate system can be chosen to satisfy $a(z, t) \equiv 0$, $c(z, t) \equiv 0$ (cf.[5]). In this paper, we are interested in a general case of the Walker metric g as in (1.1).

2. CURVATURE TENSOR OF 4-DIMENSIONAL NEUTRAL METRIC ADMITTING A PARALLEL NULL 2-PLANE

In suitable coordinates the canonical form of Walker metric has been obtained by Walker in [5, 6], where the metric expresses as in (1.1).

It follows, after some straightforward calculations, that the Levi Civita connection of a Walker metric (1.1) is given by

$$\begin{aligned} \nabla_{\partial_x} \partial_z &= \frac{1}{2} a_x \partial_x + \frac{1}{2} c_x \partial_y \\ \nabla_{\partial_x} \partial_t &= \frac{1}{2} c_x \partial_x + \frac{1}{2} b_x \partial_y \\ \nabla_{\partial_y} \partial_z &= \frac{1}{2} a_y \partial_x + \frac{1}{2} c_y \partial_y \\ \nabla_{\partial_y} \partial_t &= \frac{1}{2} c_y \partial_x + \frac{1}{2} b_y \partial_y \\ \nabla_{\partial_z} \partial_z &= \frac{1}{2} (a_z + c a_y + a a_x) \partial_x + \frac{1}{2} (2c_z - a_t + b a_y + c a_x) \partial_y - \frac{1}{2} a_x \partial_z - \frac{1}{2} a_y \partial_t \\ \nabla_{\partial_z} \partial_t &= \frac{1}{2} (a_t + c c_y + a c_x) \partial_x + \frac{1}{2} (b c_y + b_z + c c_x) \partial_y - \frac{1}{2} c_x \partial_z - \frac{1}{2} c_y \partial_t \\ \nabla_{\partial_t} \partial_t &= \frac{1}{2} (2c_t - b_z + c b_y + a b_x) \partial_x + \frac{1}{2} (b_t + b b_y + c b_x) \partial_y - \frac{1}{2} b_x \partial_z - \frac{1}{2} b_y \partial_t, \end{aligned}$$

where a_x means partial derivative $\frac{\partial}{\partial x} a(x, y, z, t)$ and ∂_k denotes the coordinate vector field $\frac{\partial}{\partial k}$, $k = x, y, z, t$. Hence, if (M, g) admits strictly parallel vector field, then the associated Levi-Civita connection satisfies

$$\begin{aligned} \nabla_{\partial_z} \partial_z &= \frac{1}{2} a_z \partial_x + \frac{1}{2} (2c_z - a_t) \partial_y \\ \nabla_{\partial_z} \partial_t &= \frac{1}{2} a_t \partial_x + \frac{1}{2} b_z \partial_y \end{aligned}$$

$$\nabla_{\partial_t} \partial_t = \frac{1}{2}(2c_t - b_z)\partial_x + \frac{1}{2}b_t\partial_y.$$

Let R denote the curvature tensor, taken with the sign convention $R(X, Y) = \nabla_{[X, Y]} - [\nabla_X, \nabla_Y]$. Then, the nonzero components of the curvature tensor of Walker metric (1.1) are computed as:

$$\begin{aligned} R_{\partial_z \partial_x} \partial_x &= \frac{1}{2}a_{xx}\partial_x + \frac{1}{2}c_{xx}\partial_y \\ R_{\partial_z \partial_x} \partial_y &= \frac{1}{2}a_{yx}\partial_x + \frac{1}{2}c_{xy}\partial_y \\ R_{\partial_z \partial_x} \partial_z &= \frac{1}{2}(ca_{yx} + aa_{xx})\partial_x + \frac{1}{4}(2c_{zx} + a_y b_x + 2ba_{yx} + 2ca_{xx} - 2a_{tx} - c_y c_x)\partial_y \\ &\quad - \frac{1}{2}a_{xx}\partial_z - \frac{1}{2}a_{yx}\partial_t \\ R_{\partial_z \partial_x} \partial_t &= \frac{1}{4}(2a_{tx} + c_x c_y + 2cc_{yx} - 2c_{xz} + 2ac_{xx} - b_x a_y)\partial_x + \frac{1}{2}(cc_{xx} + bc_{xy})\partial_y \\ &\quad - \frac{1}{2}c_{xx}\partial_z - \frac{1}{2}c_{yx}\partial_t \\ R_{\partial_t} \partial_x \partial_x &= \frac{1}{2}c_{xx}\partial_x + \frac{1}{2}b_{xx}\partial_y \\ R_{\partial_t} \partial_x \partial_y &= \frac{1}{2}c_{xy}\partial_x + \frac{1}{2}b_{yx}\partial_y \\ R_{\partial_t} \partial_x \partial_z &= \frac{1}{2}(cc_{xy} + ac_{xx})\partial_x + \frac{1}{4}(-2c_{xt} + 2b_{zx} + c_x^2 - c_x b_y + b_x c_y + 2bc_{yx} \\ &\quad - a_x b_x + 2cc_{xx})\partial_y - \frac{1}{2}c_{xx}\partial_z - \frac{1}{2}c_{xy}\partial_t \\ R_{\partial_t} \partial_x \partial_t &= \frac{1}{4}(2c_{tx} - 2b_{zx} + a_x b_x + b_y c_x - c_x^2 - b_x c_y + 2cb_{xx} + a_x b_x)\partial_x \\ &\quad + \frac{1}{2}(bb_{yx} + cb_{xx})\partial_y - \frac{1}{2}b_{xx}\partial_z - \frac{1}{2}b_{yx}\partial_t \\ R_{\partial_z} \partial_y \partial_x &= \frac{1}{2}a_{xy}\partial_x + \frac{1}{2}c_{xy}\partial_x \\ R_{\partial_z} \partial_y \partial_y &= \frac{1}{2}a_{yy}\partial_x + \frac{1}{2}c_{yy}\partial_x \\ R_{\partial_z} \partial_y \partial_z &= \frac{1}{2}(ca_{yy} + aa_{yx})\partial_x + \frac{1}{4}(2c_{zy} - 2a_{ty} + a_y b_y + 2ba_{yy} + 2ca_{xy} + a_x c_y \\ &\quad - a_y c_x - c_y^2)\partial_y - \frac{1}{2}a_{xy}\partial_z - \frac{1}{2}a_{yy}\partial_t \\ R_{\partial_z} \partial_y \partial_t &= \frac{1}{4}(2a_{ty} - 2c_{yz} + c_y^2 + 2cc_{yy} + a_y c_x - c_y a_x - b_y a_y + 2ac_{xy})\partial_x \\ &\quad + \frac{1}{2}(bc_{yy} + cc_{xy})\partial_y - \frac{1}{2}(c_{xy})\partial_z - \frac{1}{2}c_{yy}\partial_t \end{aligned}$$

$$\begin{aligned}
R_{\partial_t \partial_y} \partial_x &= \frac{1}{2} c_{xy} \partial_x + \frac{1}{2} b_{xy} \partial_y \\
R_{\partial_t \partial_y} \partial_y &= \frac{1}{2} c_{yy} \partial_y + \frac{1}{2} b_{yy} \partial_y \\
R_{\partial_t \partial_y} \partial_z &= \frac{1}{2} (cc_{yy} + ac_{xy} + c_y^2) \partial_y + \frac{1}{4} (2b_{zy} - 2c_{yt} + 2bc_{yy} + c_y c_x + 2cc_{xy} \\
&\quad - a_y b_x) \partial_y - \frac{1}{2} c_{xy} \partial_z - \frac{1}{2} c_{yy} \partial_t \\
R_{\partial_t \partial_y} \partial_t &= \frac{1}{4} (2c_{ty} - 2b_{zy} - c_y c_x + 2cb_{yy} + a_y b_x + 2ab_{xy}) \partial_x + \frac{1}{2} (bb_{yy} + cb_{xy}) \partial_y \\
&\quad - \frac{1}{2} b_{xy} \partial_z - \frac{1}{2} b_{yy} \partial_t \\
R_{\partial_t \partial_z} \partial_x &= \frac{1}{4} (2c_{xz} + b_x a_y - 2a_{tx} - c_x c_y) \partial_x + \frac{1}{4} (c_x^2 + 2b_{xz} + b_x c_y - a_x b_x \\
&\quad - 2c_{xt} - c_x b_y) \partial_y \\
R_{\partial_t \partial_z} \partial_y &= \frac{1}{4} (2c_{yz} + b_y a_y - 2a_{yt} - c_y^2 + c_y a_x - a_y c_x + c_y c_x) \partial_x \\
&\quad + \frac{1}{4} (2b_{yz} - a_y b_x - 2c_{yt}) \partial_y \\
R_{\partial_t \partial_z} \partial_z &= \frac{1}{4} (ca_x c_y - cc_x a_y - cc_y^2 - 2ca_{yt} - 2aa_{xt} + ca_y b_y + aa_y b_x + 2cc_{yz} \\
&\quad + 2ac_{xz} - ac_y c_x) \partial_x + \frac{1}{4} (2b_{zz} + 2a_{tt} - 2c_t a_x + a_x b_z - b_x a_z \\
&\quad - a_y b_t + b_y a_t - 2a_{yt} b - 2ca_{xt} + 2b_z c_y - aa_x b_x - ca_x b_y \\
&\quad + 2bc_{yz} + 2cc_{xz} - 4c_{zt} + 2c_x a_t + cc_x c_y + ac_x^2 - bc_x a_y - 2b_y c_z \\
&\quad + a_x b c_y) \partial_y + \frac{1}{4} (2a_{xt} - a_y b_x - 2c_{xz}) \partial_z \\
&\quad + \frac{1}{4} (2a_{yt} - a_y b_y + a_y c_x - 2c_{yz} - a_x c_y + c_y^2) \partial_t \\
R_{\partial_t \partial_z} \partial_t &= \frac{1}{4} (4c_{tz} - 2b_{zz} + a_z b_x + 2ab_{xz} - 2a_{tt} - b_z a_x + 2cb_{yz} + b_t a_y \\
&\quad - b_y a_t + bb_y a_y + 2c_z b_y + 2a_x c_t + ca_x b_y - ab_y c_x - 2cc_{yt} \\
&\quad - 2a_t c_x - 2ac_{xt} - 2c_y b_z - bc_y^2 - cc_x c_y + ac_y b_x) \partial_x \\
&\quad + \frac{1}{4} (cc_y b_x - 2bc_{yt} - 2cc_{xt} + bc_x c_y + cc_x^2 + 2bb_{yz} + 2cb_{xz} - b_x b a_y \\
&\quad - cb_x a_x - b_y cc_x) \partial_y + \frac{1}{4} (-2b_{xz} + b_x a_x + b_y c_x + 2c_{xt} - c_x^2 - b_x c_y) \partial_z \\
&\quad + \frac{1}{4} (b_x a_y - c_x c_y + 2c_{yt} - 2b_{yz}) \partial_t.
\end{aligned}
\tag{2.1}$$

Further note that the existence of strictly parallel vector field simplifies (2.1) as follows:

$$\begin{aligned}
R_{\partial_t \partial_z} \partial_z &= \frac{1}{2}(b_{zz} + a_{tt} - 2c_{zt})\partial_y \\
R_{\partial_t \partial_z} \partial_t &= \frac{1}{2}(2c_{tz} - b_{zz} - a_{tt})\partial_x.
\end{aligned}
\tag{2.2}$$

3. LOCALLY CONFORMAL FLAT METRICS

A semi-Riemannian manifold is locally conformal flat if and only if its Weyl tensor, given by:

$$\begin{aligned}
W(X, Y, Z, V) &= R(X, Y, Z, V) - \frac{Sc}{(n-1)(n-2)}(g(X, Z)g(Y, V) - g(X, V)g(Y, Z)) \\
&\quad - \frac{1}{(n-2)}(Ric(X, Z)g(Y, V) - Ric(Y, Z)g(X, V) + Ric(Y, V)g(X, Z)g(X, V)g(Y, Z))
\end{aligned}$$

vanishes. The nonzero components of Weyl tensor of a Walker metric (1.1) are calculated as:

$$\begin{aligned}
W(\partial_x, \partial_y, \partial_z, \partial_t) &= -\frac{1}{12}a_{xx} - \frac{1}{6}c_{xy} - \frac{1}{12}b_{yy} \\
W(\partial_x, \partial_z, \partial_x, \partial_z) &= -\frac{1}{6}a_{xx} + \frac{1}{6}c_{xy} - \frac{1}{6}b_{yy} \\
W(\partial_x, \partial_z, \partial_x, \partial_t) &= -\frac{1}{4}c_{xx} + \frac{1}{4}b_{xy} \\
W(\partial_x, \partial_z, \partial_y, \partial_z) &= -\frac{1}{4}a_{xy} + \frac{1}{4}c_{yy} \\
W(\partial_x, \partial_z, \partial_y, \partial_t) &= -\frac{1}{2}c_{yx} \\
W(\partial_x, \partial_z, \partial_z, \partial_t) &= \frac{1}{4}a_{xt} - \frac{1}{4}c_{zx} - \frac{5}{12}cc_{yx} - \frac{1}{4}bc_{yy} + \frac{1}{4}c_{yt} - \frac{1}{4}b_{zy} - \frac{1}{12}ca_{xx} \\
&\quad + \frac{1}{4}ab_{xy} + \frac{1}{6}cb_{yy} \\
W(\partial_x, \partial_t, \partial_x, \partial_t) &= -\frac{1}{2}b_{xx} \\
W(\partial_x, \partial_t, \partial_y, \partial_z) &= -\frac{1}{3}c_{yx} + \frac{1}{12}b_{yy} + \frac{1}{12}a_{xx} \\
W(\partial_x, \partial_t, \partial_y, \partial_t) &= -\frac{1}{4}b_{xy} + \frac{1}{4}c_{xx} \\
W(\partial_x, \partial_t, \partial_z, \partial_t) &= -\frac{1}{4}ab_{xx} - \frac{1}{4}cb_{xy} - \frac{1}{12}bb_{yy} - \frac{1}{12}ba_{xx} + \frac{1}{12}bc_{yx} + \frac{1}{4}cc_{xx} \\
W(\partial_y, \partial_z, \partial_y, \partial_z) &= -\frac{1}{2}a_{yy} \\
W(\partial_y, \partial_z, \partial_y, \partial_t) &= -\frac{1}{4}c_{yy} + \frac{1}{4}a_{xy}
\end{aligned}$$

$$\begin{aligned}
W(\partial_y, \partial_z, \partial_z, \partial_t) &= \frac{1}{12}aa_{xx} + \frac{1}{4}ca_{xy} + \frac{1}{4}ba_{yy} - \frac{1}{4}cc_{yy} - \frac{1}{12}ac_{yx} + \frac{1}{12}ab_{yy} \\
W(\partial_y, \partial_t, \partial_y, \partial_t) &= -\frac{1}{6}a_{xx} + \frac{1}{6}c_{xy} - \frac{1}{6}b_{yy} \\
W(\partial_y, \partial_t, \partial_z, \partial_t) &= \frac{1}{4}c_{yt} - \frac{1}{4}b_{zy} + \frac{1}{4}ac_{xx} + \frac{5}{12}cc_{yx} + \frac{1}{4}a_{xt} - \frac{1}{4}c_{zx} - \frac{1}{4}ba_{xy} \\
&\quad + \frac{1}{12}cb_{yy} - \frac{1}{6}ca_{xx} \\
W(\partial_z, \partial_t, \partial_z, \partial_t) &= \frac{1}{4}bc_xa_y - \frac{1}{4}ba_xc_y + \frac{1}{4}ab_xc_y - \frac{1}{4}ac_xb_y + \frac{1}{2}b_yc_z + \frac{1}{4}b_xa_z \\
&\quad - \frac{1}{4}a_xb_z - \frac{1}{12}baa_{xx} - \frac{1}{2}bca_{yx} + \frac{1}{2}bcc_{yy} - \frac{1}{2}c_yb_z - \frac{1}{2}cc_{yt} \\
&\quad + \frac{1}{2}cb_{zy} - \frac{1}{6}c^2b_{yy} - \frac{1}{6}c^2a_{xx} - \frac{1}{2}acb_{yx} - \frac{1}{2}cc_{zx} - \frac{1}{2}bc_{zy} \\
&\quad + \frac{1}{2}acc_{xx} + \frac{1}{3}bac_{yx} + \frac{2}{3}c^2c_{yx} - \frac{1}{2}ac_{xt} + \frac{1}{2}ba_{yt} - \frac{1}{4}b^2a_{yy} \\
&\quad + \frac{1}{2}ab_{zx} + c_{zt} - \frac{1}{4}a^2b_{xx} - \frac{1}{12}bab_{yy} + \frac{1}{2}ca_{xt} - \frac{1}{2}b_{zz} - \frac{1}{2}a_{tt} \\
(3.1) \quad &\quad + \frac{1}{4}ca_xb_y - \frac{1}{4}cb_xa_y + \frac{1}{2}a_xc_t - \frac{1}{4}b_ya_t + \frac{1}{4}a_yb_t - \frac{1}{2}c_xa_t.
\end{aligned}$$

Now it is possible to obtain the form of a locally conformal flat Walker metric as follows.

Theorem 1. *A Walker metric (1.1) is locally conformal flat if and only if the functions $a(x, y, z, t)$, $b(x, y, z, t)$ and $c(x, y, z, t)$ satisfy*

$$\begin{aligned}
a(x, y, z, t) &= F(z, t)xy + R(z, t)y - \frac{1}{2}S(z, t)x^2 + L(z, t)x + \xi(z, t) \\
b(x, y, z, t) &= xyA(z, t) + xB(z, t) + \frac{1}{2}S(z, t)y^2 + N(z, t)y + \eta(z, t) \\
(3.2) \quad c(x, y, z, t) &= \frac{1}{2}A(z, t)x^2 + M(z, t)x + \frac{1}{2}F(z, t)y^2 + H(z, t)y + \theta(z, t),
\end{aligned}$$

where the functions $R(z, t)$, $A(z, t)$, $B(z, t)$, $S(z, t)$, $Q(z, t)$, $\xi(z, t)$, $\eta(z, t)$ and $\theta(z, t)$ satisfy the following relations:

$$\begin{aligned}
LA + MS - BF - 2A_z - S_t &= 0, \\
2F_t - S_z - NF + HS + RA &= 0, \\
L_t - M_z - \eta F + H_t - N_z + \theta S + \xi A &= 0, \\
-\theta S_t - MH_t + F\eta_t + RB_t + S\eta_z - 2\xi A_t + LB_z - 2B_zH + NM_z &= 0.
\end{aligned}$$

$$\begin{aligned}
& -2S\theta_t - 2BH_z - 3MM_z + BL_z + 2BR_t + 2A\theta_z - 3A\xi_t - 2L_{tt} \\
& + 4M_{zt} - 2B_{zz} + gS_z + NH_t - NN_z + ML_t + 2hA_z = 0, \\
& 2\xi A_z - 2RM_t - 3F\eta_z - 2HH_t + 2HL_t + 2\theta S_z + RN_t + NR_t - S\xi_t \\
& + 2RB_z + 2F\theta_t - 2MR_t + BR_z + 2S\theta_z + 2LH_t - LN_z + A\xi_z \\
& - 2HM_z - 2\eta F_z - \eta HF - \eta FL - \xi AH + \xi BF + \theta NF + \theta SL \\
& - \xi MS - \theta AR - 2N_{zz} + 4H_{zt} - 2R_{tt} = 0, \\
& \eta MR + \xi BH - N\xi_t + 2\xi B_z - \xi MN + \theta NL - 2\xi M_t - \eta HL - \theta BR \\
& - 2M\xi_t + R\eta_t + 2\eta R_t + 2L\theta_t + 2\theta L_t + 2N\theta_z + B\xi_z - L\eta_z - 2\eta_z H \\
(3.3) \quad & - 2\theta H_t - 2\theta M_z + 2\theta N_z - 2\eta H_z + 4\theta_{zt} - 2\eta_{zz} - 2\xi_{tt} = 0.
\end{aligned}$$

Proof: Since a four-dimensional manifold is locally flat if and only if the Weyl tensor vanishes, we consider (3.1) as a system of PDEs.

As regards the components of the Weyl tensor (3.1) we have

$$\begin{aligned}
W(\partial_x, \partial_y, \partial_z, \partial_t) &= -\frac{1}{12}a_{xx} - \frac{1}{6}c_{xy} - \frac{1}{12}b_{yy} = 0 \\
W(\partial_x, \partial_z, \partial_x, \partial_z) &= -\frac{1}{6}a_{xx} + \frac{1}{6}c_{xy} - \frac{1}{6}b_{yy} = 0 \\
W(\partial_x, \partial_z, \partial_x, \partial_t) &= -\frac{1}{4}c_{xx} + \frac{1}{4}b_{xy} = 0 \\
W(\partial_x, \partial_z, \partial_y, \partial_z) &= -\frac{1}{4}a_{xy} + \frac{1}{4}c_{yy} = 0 \\
W(\partial_x, \partial_z, \partial_y, \partial_t) &= -\frac{1}{2}c_{yx} = 0 \\
W(\partial_x, \partial_t, \partial_x, \partial_t) &= -\frac{1}{2}b_{xx} = 0 \\
W(\partial_x, \partial_t, \partial_y, \partial_z) &= -\frac{1}{3}c_{xy} + \frac{1}{12}b_{yy} + \frac{1}{12}a_{xx} = 0 \\
W(\partial_x, \partial_t, \partial_y, \partial_t) &= -\frac{1}{4}b_{xy} + \frac{1}{4}c_{xx} = 0 \\
W(\partial_x, \partial_t, \partial_z, \partial_t) &= -\frac{1}{4}ab_{xx} - \frac{1}{4}cb_{xy} - \frac{1}{12}bb_{yy} - \frac{1}{12}ba_{xx} + \frac{1}{12}bc_{yx} + \frac{1}{4}cc_{xx} = 0 \\
W(\partial_y, \partial_z, \partial_y, \partial_z) &= -\frac{1}{2}a_{yy} = 0
\end{aligned}$$

$$\begin{aligned}
W(\partial_y, \partial_z, \partial_y, \partial_t) &= -\frac{1}{4}c_{yy} + \frac{1}{4}a_{xy} = 0 \\
W(\partial_y, \partial_z, \partial_z, \partial_t) &= \frac{1}{12}aa_{xx} + \frac{1}{4}ca_{xy} + \frac{1}{4}ba_{yy} - \frac{1}{4}cc_{yy} - \frac{1}{12}ac_{yx} + \frac{1}{12}ab_{yy} = 0 \\
(3.4) \quad W(\partial_y, \partial_t, \partial_y, \partial_t) &= -\frac{1}{6}a_{xx} + \frac{1}{6}c_{xy} - \frac{1}{6}b_{yy} = 0.
\end{aligned}$$

The above equations imply

- (1) $c_{yx} = 0$
- (2) $b_{xx} = 0$
- (3) $a_{yy} = 0$
- (4) $b_{yyx} = 0$
- (5) $b_{yyy} = 0$
- (6) $c_{xx} = b_{yx}$
- (7) $a_{yx} = c_{yy}$
- (8) $a_{xx} = -b_{yy}$
- (9) $c_{yyy} = 0$.

>From the first equation we have $c(x, y, z, t) = \bar{c}(x, z, t) + \hat{c}(y, z, t)$, and from the second equation $b(x, y, z, t) = xM_1(y, z, t) + N_1(y, z, t)$, while the third equation we get $a(x, y, z, t) = yF_1(x, z, t) + G_1(x, z, t)$.

>From the fourth and fifth equations we conclude that $M_{1yy} = 0$ and $N_{1yyy} = 0$. Therefore $M_1(y, z, t) = yA(z, t) + B(z, t)$ and

$$N_1(y, z, t) = \frac{1}{2}S(z, t)y^2 + N(z, t)y + \eta(z, t),$$

so,

$$b(x, y, z, t) = xyA(z, t) + xB(z, t) + \frac{1}{2}S(z, t)y^2 + N(z, t)y + \eta(z, t).$$

Since $c_{yyy} = 0$, we have $\hat{c}_{yyy}(y, z, t) = 0$, therefore

$$\hat{c}(y, z, t) = \frac{1}{2}F(z, t)y^2 + H(z, t)y + K_1(z, t).$$

>From $c_{xx} = b_{xy}$, we have $\bar{c}_{xx}(x, z, t) = A(z, t)$, hence,

$$\bar{c}(x, z, t) = \frac{1}{2}A(z, t)x^2 + M(z, t)x + N_2(z, t),$$

and

$$c(x, y, z, t) = \frac{1}{2}A(z, t)x^2 + M(z, t)x + \frac{1}{2}F(z, t)y^2 + H(z, t)y + \theta(z, t).$$

Since $a_{xx} = -b_{yy}$, we have $yF_{1xx}(x, z, t) + G_{1xx} = -S(z, t)$, therefore $F_{1xx} = 0$ and

$$G_1(x, z, t) = -\frac{1}{2}S(z, t)x^2 + L(z, t)x + \xi(z, t).$$

By $a_{xy} = F_{1x} = c_{yy} = F(z, t)$, we have $F_1(x, z, t) = F(z, t)x + R(z, t)$, so

$$a(x, y, z, t) = F(z, t)xy + R(z, t)y - \frac{1}{2}S(z, t)x^2 + L(z, t)x + \xi(z, t).$$

By sixth equation of (3.1)

$$W_{1334} = \frac{1}{4}a_{xt} - \frac{1}{4}c_{zx} - \frac{5}{12}cc_{yx} - \frac{1}{4}bc_{yy} + \frac{1}{4}c_{yt} - \frac{1}{4}b_{zy} - \frac{1}{12}ca_{xx} + \frac{1}{4}ab_{yx} + \frac{1}{6}cb_{yy} = 0,$$

so from the above relations we get

$$\begin{aligned} & \frac{1}{2}yF_t(z, t) + \frac{1}{4}L_t(z, t) - \frac{1}{4}xS_t(z, t) - \frac{1}{2}xA_z(z, t) - \frac{1}{4}M_z(z, t) \\ & - \frac{1}{4}yN(z, t)F(z, t) - \frac{1}{4}xB(z, t)F(z, t) - \frac{1}{4}\eta(z, t)F(z, t) + \frac{1}{4}H_t(z, t) \\ & - \frac{1}{4}N_z(z, t) - \frac{1}{4}yS_z(z, t) + \frac{1}{4}xM(z, t)S(z, t) + \frac{1}{4}yH(z, t)S(z, t) \\ & + \frac{1}{4}\theta(z, t)S(z, t) + \frac{1}{4}xL(z, t)A(z, t) + \frac{1}{4}yR(z, t)A(z, t) + \frac{1}{4}\xi(z, t)A(z, t) \equiv 0, \end{aligned}$$

and

$$\begin{aligned} W_{1334} = & \frac{1}{4}y(2F_t(z, t) - S_z(z, t) - N(z, t)F(z, t) + H(z, t)S(z, t) \\ & + R(z, t)A(z, t)) + \frac{1}{4}x(L(z, t)A(z, t) + M(z, t)S(z, t) \\ & - B(z, t)F(z, t) - 2A_z(z, t) - S_t(z, t)) + L_t(z, t) - M_z(z, t) \\ & - \eta(z, t)F(z, t) + H_t(z, t) - N_z(z, t) + \theta(z, t)S(z, t) + \xi(z, t)A(z, t) \equiv 0, \end{aligned}$$

implying the first three equations of (3.3). Similarly, from the fifteenth equation of (3.1) follow the first three equations of (3.3).

By the last equation of (3.1)

$$\begin{aligned} W_{3434} = & \frac{1}{4}bc_xa_y - \frac{1}{4}ba_xc_y + \frac{1}{4}ab_xc_y - \frac{1}{4}ac_xb_y + \frac{1}{2}b_yc_z + \frac{1}{4}b_xa_z - \frac{1}{4}a_xb_z \\ & - \frac{1}{12}baa_{xx} - \frac{1}{2}bca_{yx} + \frac{1}{2}bcc_{yy} - \frac{1}{2}c_yb_z - \frac{1}{2}cc_{yt} + \frac{1}{2}cb_{zy} - \frac{1}{6}c^2b_{yy} \\ & - \frac{1}{6}c^2a_{xx} - \frac{1}{2}acb_{yx} - \frac{1}{2}cc_{zx} - \frac{1}{2}bc_{zy} + \frac{1}{2}acc_{xx} + \frac{1}{3}bac_{yx} + \frac{2}{3}c^2c_{yx} \\ & - \frac{1}{2}ac_{xt} + \frac{1}{2}ba_{yt} - \frac{1}{4}b^2a_{yy} + \frac{1}{2}ab_{zx} + c_{zt} - \frac{1}{4}a^2b_{xx} - \frac{1}{12}bab_{yy} \\ & + \frac{1}{2}ca_{xt} - \frac{1}{2}b_{zz} - \frac{1}{2}a_{tt} + \frac{1}{4}ca_xb_y - \frac{1}{4}cb_xa_y + \frac{1}{2}a_xc_t - \frac{1}{4}b_ya_t \end{aligned}$$

$$+\frac{1}{4}a_yb_t-\frac{1}{2}c_xa_t\equiv 0,$$

implying

$$\begin{aligned} & x^3\left(\frac{1}{2}AS_t-\frac{1}{2}LA^2+AA_z+\frac{1}{2}ABF-\frac{1}{2}SMA\right)+x^2\left(-MS_t+2BF_t\right. \\ & +NA_z+\frac{1}{2}ABR-\frac{1}{2}SMN-\frac{1}{2}LAN+\frac{1}{2}SBH-\theta AS+\eta AF-LA_t-AH_t \\ & -2AL_t-\xi A^2-SM_t+AM_z+FB_t+AN_z+S_{tt}+2A_{zt}-\frac{1}{2}S_zB+\frac{1}{2}S_tN\Big) \\ & +x\left(-2\theta S_t-\theta NS-\theta BF+\eta AR+\theta AL+\eta MF+\eta HS-\xi MA-\xi AN\right. \\ & +2\eta F_t-2MH_t+F\eta_t+RB_t+S\eta_z-2\xi A_t+LB_z-2B_zH+2NM_z \\ & -2S\theta_t-NL_t+2MN_z-2BH_z-2MM_z+BL_z+2BR_t+2A\theta_z-3A\xi_t \\ & -2L_{tt}+4M_{zt}-2B_{zz}\Big)+y^3\left(\frac{1}{2}SHF-\frac{1}{2}NF^2+\frac{1}{2}RAF-\frac{1}{2}FS_z+FF_t\right) \\ & +y^2\left(-FM_z+2RA_z-\eta F^2+FH_t+LF_t+FL_t+AR_z-2FN_z-\frac{1}{2}LS_z\right. \\ & +\frac{1}{2}RS_t-NF_z+SH_z+S_zH+\theta SF+\frac{1}{2}SHL-\frac{1}{2}NFL+\xi AF+\frac{1}{2}RBF \\ & -\frac{1}{2}RMC+2F_{zt}-S_{zz}\Big)+y\left(2\xi A_z-2RM_t-3F\eta_z-2HH_t+2HL_t+2\theta S_z\right. \\ & +RN_t+NR_t-S\xi_t+2RB_z+2F\theta_t-2MR_t+BR_z+2S\theta_z+2LH_t \\ & -LN_z+A\xi_z-2HM_z-2\eta F_z-\eta HF-\eta FL-\xi AH+\xi BF+\theta NF+\theta SL \\ & -\xi MS-\theta AR-2N_{zz}+4H_{zt}-2R_{tt})+xy(-\theta S^2+AL_z+SN_z+FN_t \\ & -BF_z-2A_zH+2MS_z-2MF_t+LA_z+NF_t-2SH_t-2HS_t-AR_t-SL_t \\ & -FB_z-RA_t+2SM_z+FMN+\eta FS-FBH-fAS-RMA+LAH \\ & -2F_{tt}-2A_{zz}\Big)+xy^2\left(\frac{1}{2}SS_z-\frac{1}{2}FS_t-SF_t-FA_z-\frac{1}{2}S^2H-\frac{1}{2}F^2B\right. \\ & +\frac{1}{2}LAF-\frac{1}{2}RAS+\frac{1}{2}FMS+\frac{1}{2}NFS\Big)+x^2y\left(-\frac{1}{2}SAH+SA_z+\frac{1}{2}SS_t\right. \\ & -AF_t-\frac{1}{2}S^2M+\frac{1}{2}AS_z-\frac{1}{2}RA^2+\frac{1}{2}SBF-\frac{1}{2}LAS+\frac{1}{2}FAN\Big)+\eta MR \\ & +\xi BH-N\xi_t+2\xi B_z-\xi MN+\theta NL-2\xi M_t-\eta HL-\theta BR-2M\xi_t+R\eta_t \\ & +2\eta R_t+2L\theta_t+2\theta L_t+2N\theta_z+B\xi_z-L\eta_z-2\eta_zH-2\theta H_t-2\theta M_z+2\theta N_z \\ & -2\eta H_z+4\theta_{zt}-2\eta_{zz}-2\xi_{tt}\equiv 0, \end{aligned}$$

from where, the three equations of (3.3) follow.

Definition 2. Let Ric and Sc denote Ricci tensor and scalar curvature of (M, g) , defined by $Ric = \text{trace} \{Z \rightarrow R(X, Z)Y\}$ and $Sc = \text{trace } Ric$, respectively.

Lemma 1. The scalar curvature of a Walker metric (1.1) is given by

$$(3.5) \quad Sc = b_{yy} + a_{xx} + 2c_{xy}$$

Proof: The nonzero components of the Ricci tensor of any Walker metric (1.1) are as follows

$$\begin{aligned} Ric(X_1, X_3) &= \frac{1}{2}a_{xx} + \frac{1}{2}c_{xy} \\ Ric(X_1, X_4) &= \frac{1}{2}c_{xx} + \frac{1}{2}b_{xy} \\ Ric(X_2, X_3) &= \frac{1}{2}a_{xy} + \frac{1}{2}c_{yy} \\ Ric(X_2, X_4) &= \frac{1}{2}c_{xy} + \frac{1}{2}b_{yy} \\ Ric(X_3, X_1) &= \frac{1}{2}a_{xx} + \frac{1}{2}c_{xy} \\ Ric(X_3, X_2) &= \frac{1}{2}a_{xy} + \frac{1}{2}c_{yy} \\ Ric(X_3, X_3) &= \frac{1}{2} \left(2ca_{xy} + aa_{xx} + ba_{yy} + a_y b_y - 2a_{yt} + a_x c_y \right. \\ &\quad \left. - a_y c_x + 2c_{zy} - c_y^2 \right) \\ Ric(X_3, X_4) &= \frac{1}{2} \left(a_{tx} - a_y b_x + b_{yz} + ac_{xx} + 2cc_{xy} - c_{xz} + bc_{yy} - c_{yt} + c_x c_y \right) \\ Ric(X_4, X_1) &= \frac{1}{2}c_{xx} + \frac{1}{2}b_{xy} \\ Ric(X_4, X_2) &= \frac{1}{2}c_{xy} + \frac{1}{2}b_{yy} \\ Ric(X_4, X_3) &= \frac{1}{2} \left(ac_{xx} + 2cc_{xy} + a_{tx} - c_{xz} + c_x c_y + bc_{yy} - c_{yt} - a_y b_x + b_{yz} \right) \\ Ric(X_4, X_4) &= \frac{1}{2} \left(-2b_{zx} + a_x b_x + cb_{xy} + cb_{xx} + bb_{yy} + 2c_{xt} - c_x^2 - b_x c_y + c_x b_y \right). \end{aligned}$$

The equations expressing the components of the curvature tensor ensure that the Ricci operator $\langle \hat{Ric}(X), Y \rangle = Ric(X, Y)$ satisfies

$$\hat{Ric}(\partial_x) = \left(\frac{1}{2}a_{xx} + \frac{1}{2}c_{xy} \right) \partial_x + \left(\frac{1}{2}a_{xy} + \frac{1}{2}c_{yy} \right) \partial_y$$

$$\begin{aligned}
\widehat{Ric}(\partial_y) &= \left(\frac{1}{2}a_{xy} + \frac{1}{2}c_{yy}\right)\partial_x + \left(\frac{1}{2}c_{xy} + \frac{1}{2}b_{yy}\right)\partial_y \\
\widehat{Ric}(\partial_z) &= \frac{1}{2}\left(2ca_{xy} + aa_{xx} + ba_{yy} + a_yb_y - 2a_{yt} + a_xc_y - a_yc_x + 2c_{zy} - c_y^2\right)\partial_x \\
&\quad + \frac{1}{2}\left(a_{tx} - a_yb_x + b_{yz} + ac_{xx} + 2cc_{xy} - c_{xz} + bc_{yy} - c_{yt} + c_xc_y\right)\partial_y \\
&\quad + \left(\frac{1}{2}a_{xx} + \frac{1}{2}c_{xy}\right)\partial_z + \left(\frac{1}{2}a_{xy} + \frac{1}{2}c_{yy}\right)\partial_t \\
\widehat{Ric}(\partial_t) &= \frac{1}{2}\left(ac_{xx} + 2cc_{xy} + a_{tx} - c_{xz} + c_xc_y + bc_{yy} - c_{yt} - a_yb_x + b_{yz}\right)\partial_x \\
&\quad + \frac{1}{2}\left(-2b_{zx} + a_xb_x + cb_{xy} + cb_{xx} + bb_{yy} + 2c_{xt} - c_x^2 - b_xc_y + c_xb_y\right)\partial_y \\
&\quad + \left(\frac{1}{2}c_{xx} + \frac{1}{2}b_{xy}\right)\partial_z + \left(\frac{1}{2}a_{xx} + \frac{1}{2}c_{xy}\right)\partial_t.
\end{aligned}$$

Now the result follows by a straightforward calculation.

Remark 1. *It follows from Lemma 1 that any locally conformal flat Walker metric has vanishing scalar curvature.*

Hence we come to semi-Riemannian manifolds with harmonic curvature (cf. [7]).

СПИСОК ЛИТЕРАТУРЫ

- [1] S. Azimpour, M. Chaichi, M. Toomanian, "A Note on 4-Dimension Locally Conformally Flat Walker Manifold", *Izv. NAN Armenii, Matematika [Journal of Contemporary Mathematical Analysis (Armenian Academy of Sciences)]* **42** (5), 219-226 (2007).
- [2] B. O'Neill, *Semi-Riemannian Geometry, With Applications to Relativity* (Academic Press, New York, 1983).
- [3] M. Chaichi, E. García-Río, and Y. Matsushita, "Curvature Properties of Four-Dimensional Walker Metrics", *Classical and Quantum Gravity* **22**, 559-577 (2005).
- [4] S. Kobayashi, K. Nomizu, *Foundations of Differential Geometry I, II* (Interscience, New York, 1969).
- [5] A. G. Walker, "Canonical Form for a Riemannian Space With a Parallel Field of Null Planes", *Quart. J. Math., Oxford* **(2)1**, 69-79 (1950).
- [6] A. G. Walker, "Canonical Forms. II. Parallel Partially Null Planes", *Quart. J. Math. Oxford* **(2)1** 147-152 (1950).
- [7] A. Derdzinski, "On Compact Riemannian Manifolds With Harmonic Curvature", *Math. Ann* **259** 145-152 (1982).

Поступила 11 января 2008